



Ideas for adding generic HW accelerators to DPDK

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Problem Statement

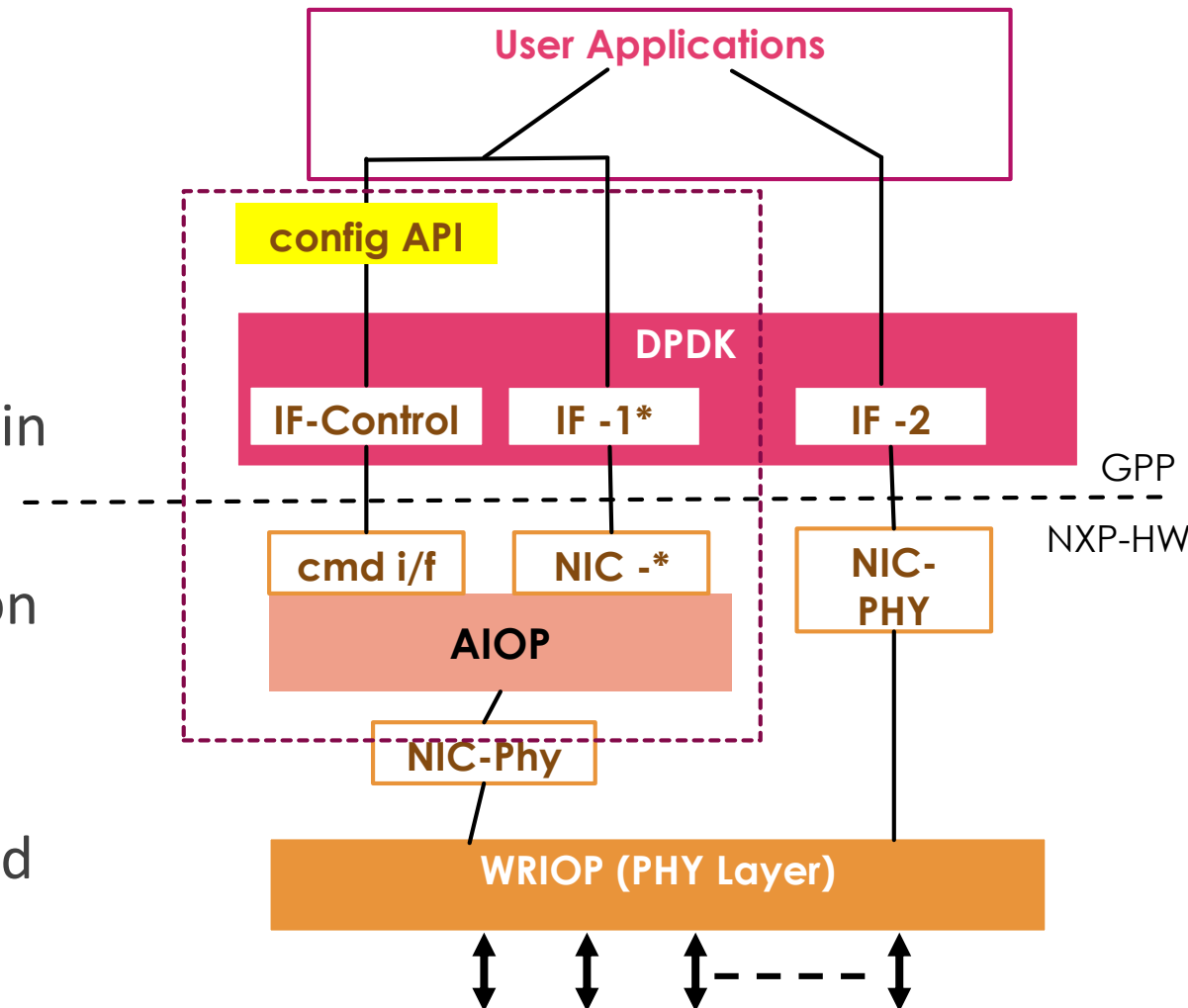


- ▶ SoCs may have many types of different accelerators, which may not be common or use completely different set of capabilities.
- ▶ How to expose them via DPDK?
 - Should we create new flavor of device type for each unique accelerator?
 - The applications using these accelerator may not be portable across architectures.

An offload use-case of NXP



- ▶ NXP Platform has a programmable engine, called 'AIOP'
- ▶ The engine can expose a NIC interface and a command-control interface for GPP-side, detectable on fsl-mc bus.
- ▶ The application needs to configure the engine in order to use it.
- ▶ NXP provides a library exposing the application level APIs and convert them to command messages.
- ▶ Some of the example use-cases are ovs offload or wireless offload.



Why in DPDK?



- ▶ Why to add it into DPDK and not use vendor specific SDK APIs.
 - Application prefers uniform device view: Start/Stop, queue/ring config
 - Uniform programming model across devices – ease of application development for users
 - Some of these accelerators may need closer integration e.g. eventdev – single place to get all events.
- ▶ Can we find a common ground for such – differently configured – accelerators in DPDK?
 - Management – difficult to find a common/generic ground
 - Input/output – Can be abstracted out.

Requirements for Accelerators Interfacing



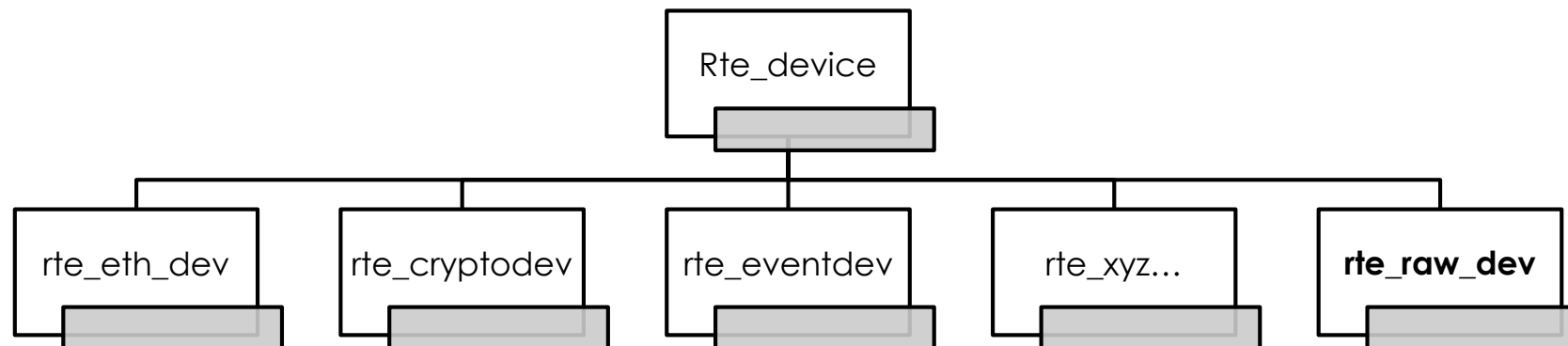
An abstract, generic APIs for applications to program hardware without knowing the details of programmable devices.

- ✓ **Command/Control APIs** – Add, delete, enable, disable, modify, config - *services* etc.
 - Synchronous or Asynchronous request/response model
- ✓ **Data I/O APIs** – enqueue/dequeue.
- ✓ **Query APIs** – Query details: Status, statistics etc.
- ✓ **Notification APIs** – unsolicited notifications generated by the offload engine. Example : logs, events, exception packets etc.
- ✓ **Firmware Management** - load/unload/status of the firmware image.

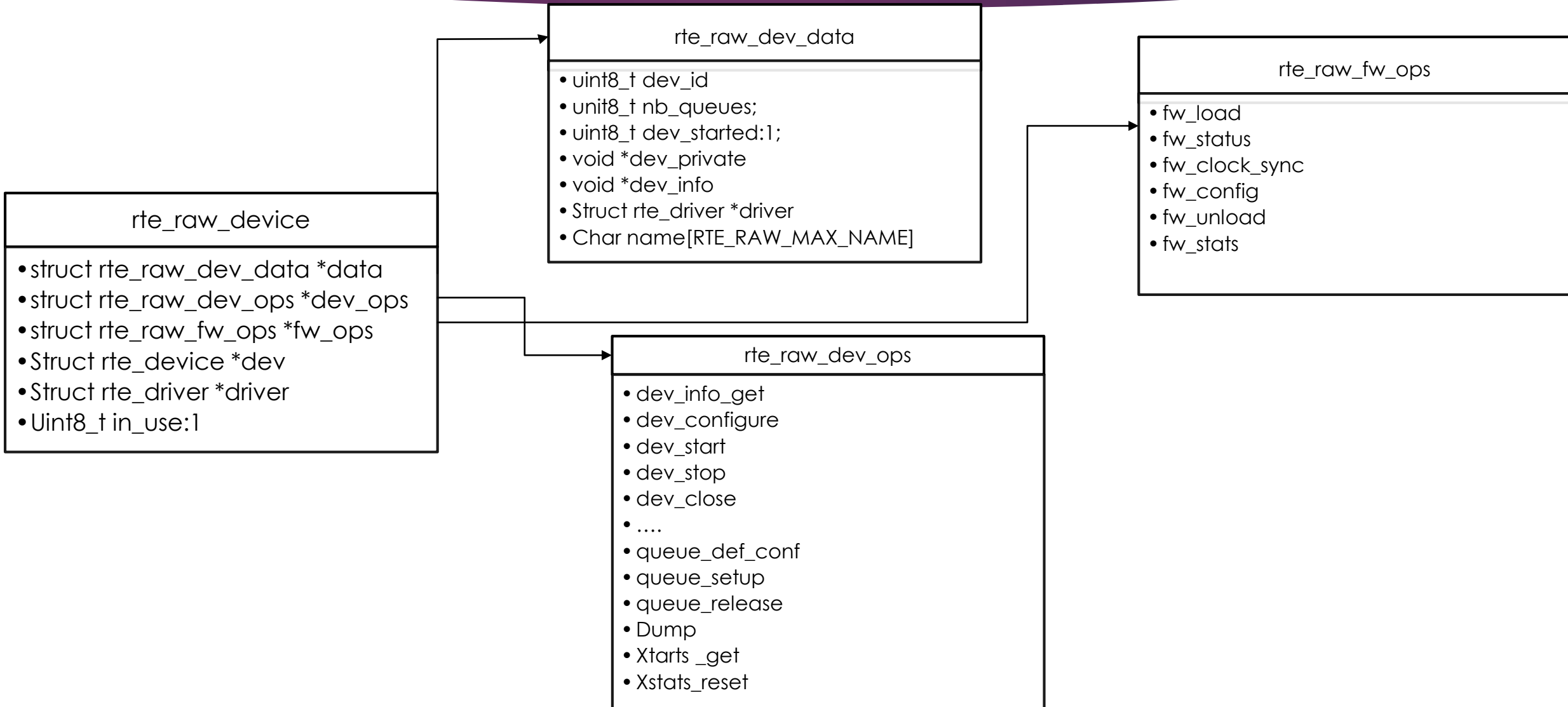
Introducing `rte_raw_device`



- ▶ A `*rte_raw_device*` is a raw/generic device without any standard configuration or input/output method assumption.
- ▶ An virtual device – on demand creation by the applications.
- ▶ The configure, info operation will be opaque structures.
- ▶ The queue/ring operations will not assume any data or buffer format.
- ▶ Specific PMDs should expose any specific config APIs – not expecting portability.



Properties for raw device



What is different from rte_prgdev ?



- ▶ The last proposal of `rte_prgdev`, mainly focused on firmware image management.
- ▶ `rte_raw_dev` focus is attempting to provide a uniform device view and accelerator access to the applications.
- ▶ `rte_raw_dev` is not discounting firmware management, but makes it an optional component.
- ▶ `rte_raw_dev` can serve as a staging device for un-common newly added device flavors.
 - ▶ Any commonly used `rte_raw` based device can be converted into it's own specific flavor.

Questions?

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SoCs – Flexible Programming Architecture



GPP Core

Control Path Cores

GPP Core (2)

Data Path Cores

DPAA

HW Engine

Controller (1)

PCD

Eth

SEC

Pattern

Data Comp

➤ Packet Processing

➤ (1) Autonomous:

Packets are received, processed and sent within the HW Engine. HW engine controller can be programmed with different autonomous applications.

➤ (1) & (2) Semi Autonomous: Packets are received by HW Engine. HW Engine controller does part of processing. GPP cores do rest of processing and send the result packets out.

➤ (2) Non-Autonomous:

Entire packet processing happens within GPP cores with no help from HW controller.

➤ Other acceleration – any kind of HW offload.

➤ Pattern Matching

➤ Data Compression